

Curriculum Vitae OF TENG TECK HOU

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CAREER OBJECTIVES

To advance the use of machine learning techniques in robotic systems for allowing it to operate autonomously in complex and unmodified environment

EDUCATION

08/2006 – 02/2013: Nanyang Technological University, Singapore

Doctor of Philosophy (Degree conferred on 7th Feb 2013)

Thesis Topic: Cognitive Information Systems for Context-Aware Decision Support

CGPA: 3.92

Impact ([Google Scholar](https://scholar.google.com/citations?user=...)) - Citation: 111, h-index: 4, i10-index: 2

Publications - Journal Articles: 4, Conference Papers: 8

Collaboration

[1] 08/2010 – 11/2011: Collaborated with DSO, TL@NUS and CAE to investigate the use of machine learning technique for knowledge discovery using CAE Strike CGF® simulation platform

[2] 02/11/2011 – 11/11/2011: Demonstrated the machine learning technique to CAE at Montreal, Canada involving CAE Test Pilots engaging in simulated dogfights with the AI-driven agent

Talk/Seminar

[1] Technical sharing on Adaptive CGF Technology, CAE™ Inc., Montreal Canada, 9th November 2011

[2] Self-Organizing Neural Networks for Learning Air Combat Maneuvers, ER-LAB @ NTU, Singapore, 5th June 2012

Teaching/Supervisory Experience

[1] Jul 2007 – Oct 2007, Jul 2010 – Oct 2010: Supervision of laboratory sessions

Peer-review Experience

[1] **Conference:** AAMAS, Fusion, IAT, ICDM, IEA-AIE, IRI, ISNN, IWACI, ICONIP

[2] **Journal:** Applied Intelligence, JAISE, SMC-A, TNN, IEEE-Cybernetics, Applied Soft Computing, TKDE, TNN-LS

Committee Membership

[1] **Program Committee:** Aml 2013, Aml 2014, BIH 2014

[2] **Technical Committee:** Pattern Analysis and Machine Intelligence

[3] **Task Force:** ADP in Game Theory and Multi-Agent Optimization, Real-Time Strategy Games

Research Interests

[1] Reinforcement Learning: adaptive resonance theory, perceptual aliasing, design of reward function, exploration and exploitation strategies

[2] Behavior Modeling: use of state machine architecture for modeling complex behaviors

[3] Application domains: Zero-sum Markov Decision Processes, Machine learning on problem domains with complex knowledge structure, Modeling and forecasting of complex phenomenon

2000 – 2003: Nanyang Technological University, Singapore

Bachelor of Engineering (Computer Engineering)

Honor: 2nd Class (Upper Division)

Final Year Project (Awarded ‘A’ grade): Identification and tracking of dim moving targets in FLIR imagery using artificial neural networks

[1] **Teck-Hou Teng**, Patra J. C. and Ee-Luang Ang, Identification and tracking of dim moving targets in FLIR using artificial neural networks, In proceedings, Seventh International Symposium on Signal Processing and Its Application(ISSPA), 223-226, Vol. 2, Paris, 1-4 July 2003

1995 – 1998: Singapore Polytechnic

Diploma with Merit in Electronics, Computer and Communication

Major: Telecommunication

Final Year Project: Mobile Robotics (sensory circuit and exploration algorithms)

1991 – 1994: Mayflower Secondary School

GCE ‘O’ Level: Scored 4 distinctions out of 8 subjects

WORK EXPERIENCE

SIM University (UniSIM), School of Business, Business Analytics Programme

Instructor (01/2014 – present)

- ANL303e Fundamentals of Data Mining (01/2014 – present)

Nanyang Technological University, School of Computer Engineering, Center for Computational Intelligence

Project Officer (02/2012 – 03/2013), Research Fellow (04/2013 – Present)

- Develops AI Engine used on a Multi-Player Computer Game *Starcraft Broodwar* for a DSO-funded project
- Coordinates multi-agent reinforcement learning for a learning problem with multiple tasks and goals
- Uses self-organizing neural network to discover effective rules incrementally in real time
- Suitable for problems involving multiple goals with task dependencies and resource competition

**Temasek Laboratories @ NTU, Modeling & Simulation Systems Laboratory of
Project Officer (03/02/2004 – 01/08/2006)**

- Developed AI Engine for a DSTA-funded Urban Warfare Simulator.
- Knowledgeable in research topics such Cognitive Architecture, FSM, Motion Control, Synthetic Vision, Path Planning, MADM, Evidential Reasoning, Fuzzy Logic, Genetic Algorithms, Neural Networks.

**Sembawang Airbase, Air Logistic Squadron, Air Weapons Flight
Technician (01/02/99 - 30/06 /00 & 01/07/2003 - 27/01/2004)**

- Specialized in various armament systems (GPMGs and Gun Pod) for helicopters.
- Worked within a stringent set of engineering protocols.

**INRIA Rhoné Alpes, Grenoble, France
Trainee, 07 January 2002 – 22 June 2002**

- Involved in the development of a simulator for the electric vehicle, the Cycab.
- Worked on the Automatic Controller Development program called the ORCCAD.

**SMP Electronics Pte. Ltd., Singapore
Technical Support, July 1998 – October 1998**

- Involved in configuring HP Palmtops for use by AIA Insurance Agents.
- Completed a few freelance projects which involved building several test board for Alcatel's line of handphones.

**University of Salford, Salford, Manchester
Research Student, 12 May 1997 – 30 June 1997**

- Involved in the electrical and mechanical design of a **dexterous robotic hand** for the robotic research laboratory of the Acoustic and Electronics Department.

ACTIVITIES AND HONOURS

Overseas Industrial Attachment

- Completed a virtual navigation platform for an autonomous robot, the Cycab, in a virtual environment while with INRIA Rhoné Alpes, France under the supervisor of **Daniel Simon**.
- Awarded an '**A**' grade for my contributions in the Industrial Attachment Programme (NTU) to **INRIA Rhoné Alpes**.

Book Prizes and Awards

- Awarded **Mentor Graphics Prize** for meritorious academic performance in my second year in Singapore Polytechnic.
- Awarded **ILOG Prize** for meritorious academic performance in my final year in Singapore Polytechnic.
- Awarded **Nanyang Award - Teamwork** for participation in Run Round Singapore 2010
- Awarded **Nanyang Alumni Service Award** for recognition of effort towards NTU Endowment

Fund Raising activities

- Awarded **SAF Good Service Medal (5 years)** for commitment and dedication to routine In-Camp Training

Competitions

- Competed in the **Obstacle Avoidance Robot** in Singapore Robotics Games 1998 using the Final Year Project in Singapore Polytechnic (1995 –1998).

Exhibitions

- 3G SAF TechX Exhibition at Suntec Convention and Exhibition Centre, Level 2, Ballroom 1 – 3 from 11 – 12 November 2004.

SKILLS

Technical Skills

- Operating System: Windows (XP, Vista, 7), Ubuntu (linux)
- Programming Language: C++, Java and Matlab
- Scripting Language: Luaplus, XML, HTML
- Documentation: Latex, UML, Microsoft Office (Excel, Word, Powerpoint, Visio), Techsmith Snagit (screen capture and video editing)
- Development & Simulation Software: Visual Studio C++, Eclipse IDE, CAE Strike™ CGF, SPSS Modeler (version 14.1)

Foreign Language

- Participated in **3 years of French Language course** in Singapore Polytechnics.
- Completed French Language course in **Centre Universitaire d'Etudes Franaises (CUEF)**, Université Stendhal, Grenoble, France.

Referees

Dr. Ah-Hwee Tan
Associate Professor
School of Computer Engineering,
Nanyang Technological University

Dr. Janusz A. Starzyk
Professor
School of Electrical Engineering
and Computer Science,
Ohio University

Mr. Wee-Sze Ong
Programme Manager
Information Division,
DSO National Laboratories

List of Publications

[1] **Teck-Hou, Teng**, Ah-Hwee Tan, Jacek M. Zurada, Self-Organizing Neural Networks Integrating Domain Knowledge and Reinforcement Learning, IEEE Transactions on Neural Networks and Learning Systems, DOI 10.1109/TNNLS/2014.2327636, 2014

[2] **Teck-Hou, Teng**, Ah-Hwee Tan and Loo-Nin Teow, *Adaptive Computer-Generated Forces For Simulator-based Training. Expert Systems with Application*, Vol. 40, No. 18, pp. 7341-7353, December 2013

- [3] Yu-Hong Feng, **Teck-Hou, Teng** and Ah-Hwee Tan, *Modeling Situation Awareness for Context-Aware Decision Support, Expert Systems with Application*, Vol. 36, No. 1, pp. 455-463, January 2009
- [4] **Teck-Hou Teng**, Jagdish C. Patra and Ee-Luang Ang. *Identification and Tracking of Dim Moving Targets in FLIR Imagery using Artificial Neural Networks*. In Proceedings of the 7th International Symposium on Signal Processing and its Applications, Vol. 2 pp. 223-226, Paris, July 2003
- [5] **Teck-Hou Teng** and Ah-Hwee Tan, *Cognitive Agents Integrating Rules and Reinforcement Learning for Context-Aware Decision Support*, In proceedings of the IEEE/WIC/ACM International Conference on Intelligent Agent Technology, Sydney, 9-12 December 2008
- [6] **Teck-Hou Teng**, Zhong-Ming Tan and Ah-Hwee Tan, *Self-Organizing Neural Models Integrating Rules and Reinforcement Learning*, In proceedings of the International Joint Conference on Neural Networks, pp. 3770-3777, Hong Kong SAR, 1-6 June 2008
- [7] **Teck-Hou Teng**, Ah-Hwee Tan, Yuan-Sin Tan and Adrian Yeo. *Self-Organizing Neural Networks for Learning Air Combat Maneuvers*. In Proceedings of the International Joint Conference on Neural Networks, pp. 2859-2866, Brisbane, June 2012
- [8] **Teck-Hou Teng**, Ah-Hwee Tan, Wee-Sze Ong and Kien-Lip Lee. *Adaptive CGF for Pilots Training in Air Combat Simulation*. In Proceedings of the 15th International Conference on Information Fusion, pp. 2263-2270, July 2012
- [9] **Teck-Hou Teng**, Ah-Hwee Tan and Yuan-Sin Tan. *Self-Regulating Action Exploration in Reinforcement Learning*. *Procedia Computer Science*, 13:62-74, 2012
- [10] **Teck-Hou Teng** and Ah-Hwee Tan. *Knowledge-based Exploration for Reinforcement Learning in Self-Organizing Neural Networks*. In Proceedings of the International Conference on Intelligent Agent Technology, pp. 332-339, Macau SAR, Dec 2012
- [11] **Teck-Hou Teng** and Ah-Hwee Tan. *Delayed Insertion and Rule Effect Moderation of Domain Knowledge for Reinforcement Learning*. In Proceedings of the IEEE Symposium on Adaptive Dynamic Programming and Reinforcement Learning, pp. 132-139, Singapore, April 2013
- [12] **Teck-Hou Teng**, Ah-Hwee Tan, Janusz. A. Starzyk, Yuan-Sin Tan and Loo-Nin Teow. *Integrating Self-Organizing Neural Network and Motivated Learning for Coordinated Multi-Agent Reinforcement Learning in Multi-Stage Stochastic Game*. In Proceedings of the International Joint Conference on Neural Networks (IJCNN'14), pp. 4229-4236, Beijing, 2014.
- [13] **Teck-Hou Teng**, Ah-Hwee Tan, Janusz. A. Starzyk, Yuan-Sin Tan and Loo-Nin Teow. *Integrating Motivated Learning and k-Winner-Take-All to coordinate Multi-Agent Reinforcement Learning*. In Proceedings of the International Conference on Intelligent Agent Technology (IAT'14), pp. 190-197, Warsaw, 2014.